



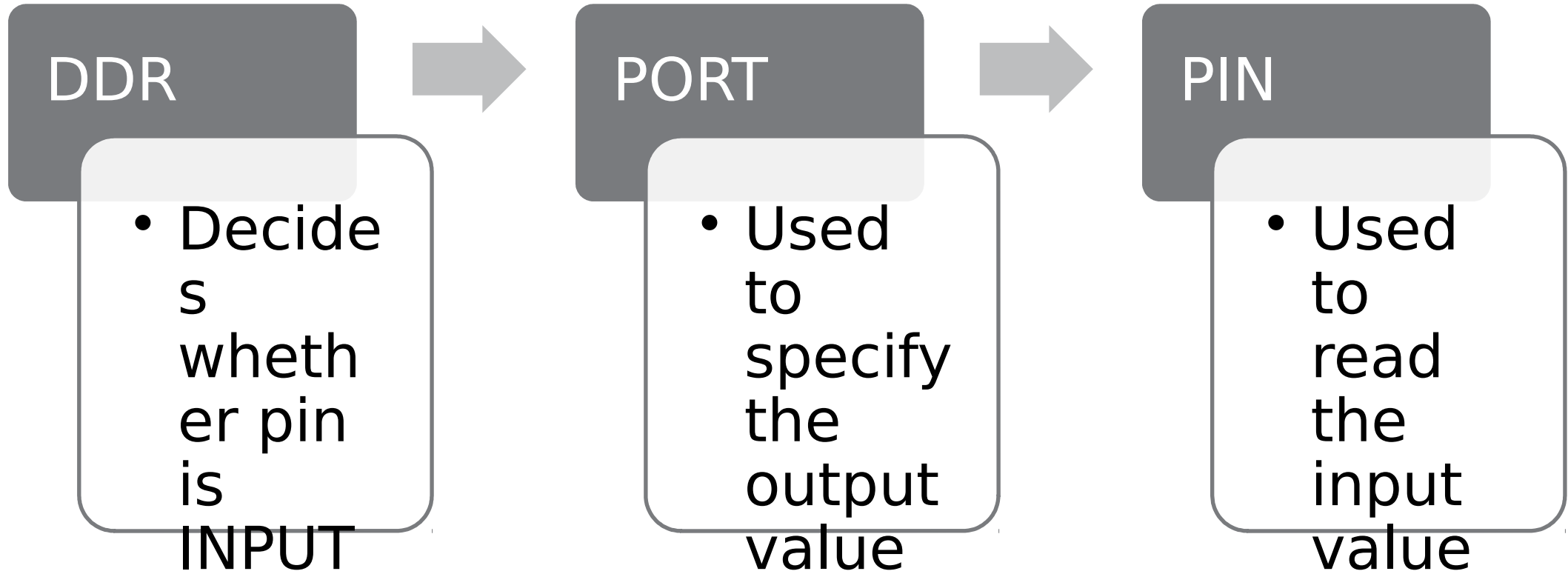
TIMERS AND INTERRUPTS

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RECAP



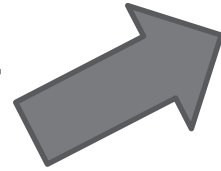
REGISTERS



or
OUTPUT

SOFTWARE NEEDED

**CVAV
R**



**Extreme
Burner
AVR**

SIMPLE STATISTICS

Maximum value of timer is n and clock period is t , then:

1. Timer period = t
2. Timer cycle period = $(n+1) \times t$
3. Frequency of timer (f) = $1/t$
4. Frequency of timer cycle = $1/(n+1) \times t$

TIMER MODES

A timer works in three modes: Normal, CTC and PWM

Normal mode: Timer starts at zero, goes to maximum value and then resets itself

CTC (Clear Timer on Compare), clearly the timer starts at zero as usual, but instead of resetting after maximum value, it resets after reaching value specified in OCR register

PWM(Pulse Width Modulation) can be used to obtain analog values at the pins

SUPPOSE YOU NEED TO CHECK FOR A CONDITION A WHILE RUNNING ANOTHER CONDITION B

```
while(1){  
---- -> if (Event A == true)  
---- -> // print event A has occurred  
----  
----  
---- -> Event B  
---- -> Suppose Event A happens  
---- here  
----  
}
```

Do you see the problem in this approach??

A BETTER SOLUTION: INTERRUPT

Interrupts means causing a break in a continuing process.

We execute the Event B in a normal while(1) loop.

```
.  
while(1){  
  ---  
  ---  
  EVENT B  
  ---  
  ---  
}  
.
```

We will consider the occurrence of event A as an interrupt



```
.  
while(1){  
---  
---  
EVENT B  
---  
---  
}  
.br/>handleA(){  
.br/>---  
} // print event A has occurred
```



We execute the required code in handler of event A

MORE ON INTERRUPTS

Interrupts are special events that can “interrupt” the normal flow of a program.

Whenever an Interrupt is called, the processor stops the normal program, handles the interrupt, and then resumes its normal work.

There are two types of interrupts:

1. External
2. Internal

EXTERNAL INTERRUPTS

The controller monitors the input at the special pins INT0 and INT1, whenever external interrupt is set on.

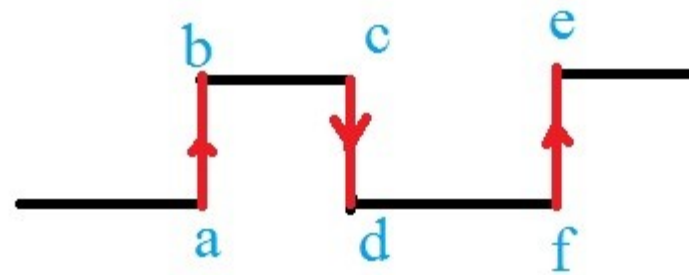
We can configure the program to call an external interrupt whenever any of the following conditions are met.

Rising Edge

Falling Edge

Any change

Low level



INTERNAL INTERRUPTS

The internal interrupts are called when different specific conditions are met by the timer value.

Timers can generate certain interrupts: two, to be precise.

These are called OVERFLOW interrupt and COMPARE MATCH interrupt.

OVERFLOW INTERRUPTS

An overflow interrupt is generated when the timer exceeds its maximum value and resets to 0.

The interrupt may or may not have a handler. In either case, the timer continues to run; remember: timers are independent of the CPU.

Suppose a timer of maximum value n has a time period t (also called as clock period).

Then :

1. Timer cycle frequency = $1/(n+1) \times t$
2. OVERFLOW interrupt frequency = $1/(n+1) \times t$

If OVERFLOW interrupt is enabled, then an interrupt is generated in every cycle.

COMPARE MATCH INTERRUPT

A compare match interrupt is called when the value of the timer equals a specific value, set by the user.

This value is set by setting the value of OCR register.

Before incrementing, the value of the timer is compared to OCR. If the two are equal, a COMPARE MATCH interrupt is generated.

Suppose a timer of maximum value n has a time period t (also called as clock period).

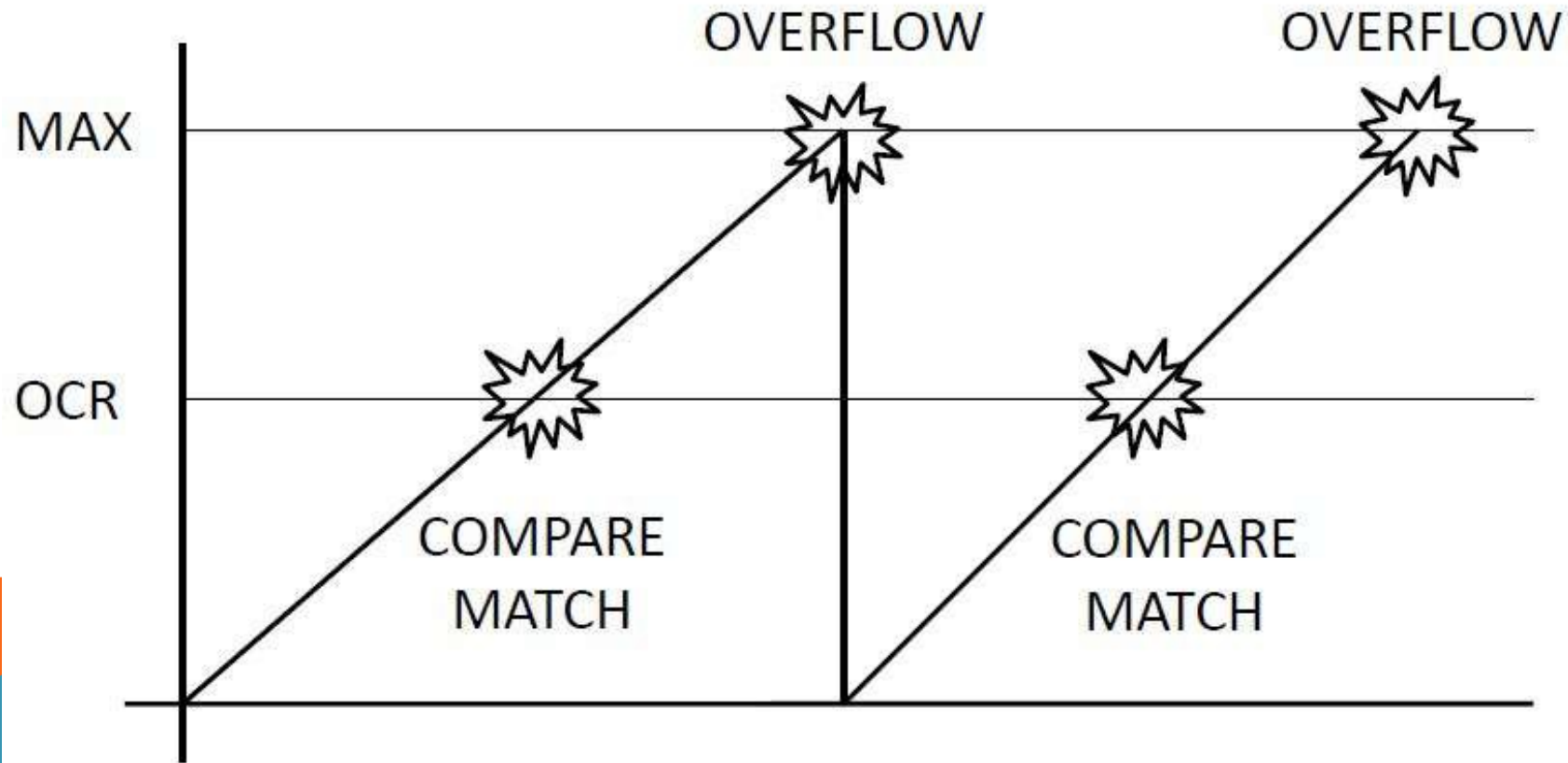
Then :

1. Timer cycle frequency = $1/(n+1) \times t$

2. COMPARE MATCH interrupt frequency = $1/(n+1) \times t$

If COMPARE MATCH interrupt is enabled, then an interrupt is generated in every cycle.

INTERRUPTS: OVERFLOW AND COMPARE MATCH



TIMERS AND INTERRUPTS

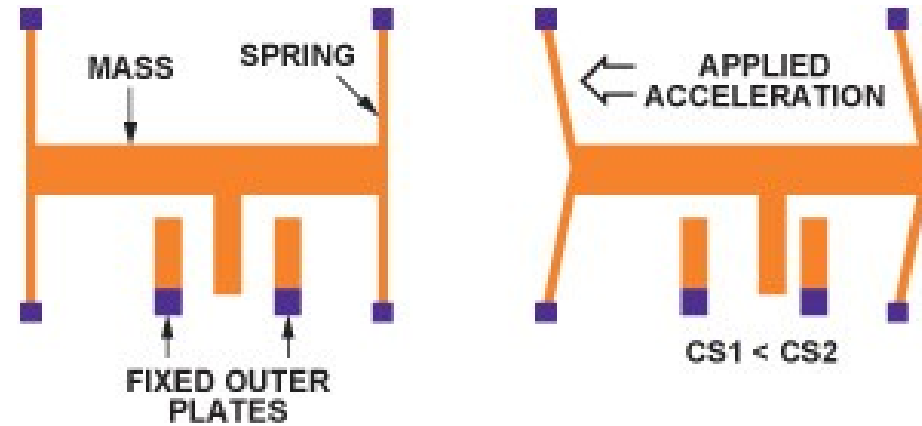
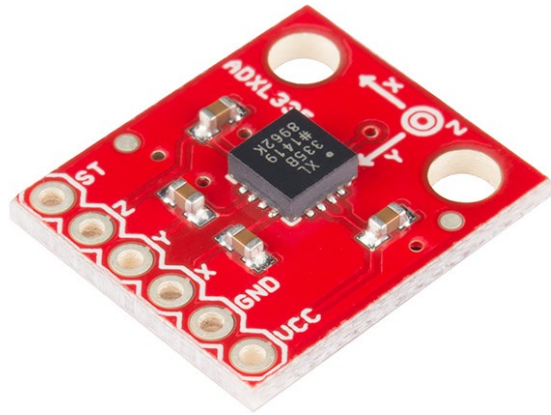
All three timer modes differ in the response of the controller to the interrupts generated

OVERFLOW and COMPARE MATCH interrupts generated as normal in NORMAL timer mode

Compare match interrupt if enabled will be generated but not overflow interrupt (Why?)

ACCELEROMETER

For Electromania this year, the standard issue board will be one based on an Analog 3-Axis MEMS Accelerometer



Poll values using Analog Input pins and scale appropriately to acquire the acceleration due to gravity on each axis and hence orientation

Refer to the datasheet for scaling information

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